

⌋

Esercizio 2

$$\Phi_\lambda(x, y) = (xy - \arctan(xy), x^2y + 4\lambda y)$$

$$(2) \quad D_1 \Phi_{\lambda,1}(x, y) = \frac{x^2 y^3}{1+(xy)^2}, \quad D_1 \Phi_{\lambda,2}(x, y) = 2xy$$

$$D_2 \Phi_{\lambda,1}(x, y) = \frac{x^3 y^2}{1+(xy)^2}, \quad D_2 \Phi_{\lambda,2}(x, y) = x^2 + 4\lambda$$

da cui

$$\det J \Phi_\lambda(x, y) = \frac{(4\lambda - x^2)x^2 y^3}{1+(xy)^2} = 0 \iff$$

$$(*) \quad x=0 \quad \vee \quad y=0 \quad \vee \quad x = \pm 2\sqrt{\lambda}$$

Affinché il cerchio aperto B_λ di raggio 1 e centro in $(1, \lambda)$ non intersechi una delle rette (*), occorre e basta che

$$\begin{cases} 2 \leq 2\sqrt{\lambda} \\ \lambda > 1 \end{cases} \iff \lambda \geq 1$$

$$(ii) \quad \text{Si ha } \det J \Phi_\lambda(x, y) = \frac{(4-x^2)x^2 y^3}{1+(xy)^2} > 0$$

se $0 < x < 2$ e $y > 0$. Dunque

$$\begin{aligned} \iint_{\Phi_1(T)} du dv &= \iint \det J \Phi_1(x, y) dx dy = \\ &= \int_1^2 dx \int_0^{x^{-1}} \frac{(4-x^2)x^2 y^3}{1+(xy)^2} dy = \frac{1}{2} \int_1^2 (4-x^2) dx. \end{aligned}$$

$$\int_0^{x^{-2}} \frac{x^2 t}{1+x^2 t} dt = \frac{1}{2} \int_0^2 (4-x^2) \left[t + \right. \\ \left. - \frac{1}{x^2} \log(1+x^2 t) \right]_0^{x^{-2}} dx = \frac{1-\log 2}{2} \int_1^2 \frac{4-x^2}{x^2} dx = \\ = \frac{1-\log 2}{2}$$

Esercizio 3

(i) La superficie sferica di equazione

$$x^2 + (y-1)^2 + (z-1)^2 = 4$$

si parametrizza in modo standard

$$\begin{cases} x = 2 \cos \theta \sin \varphi \\ y = 1 + 2 \sin \theta \sin \varphi \\ z = 1 + 2 \cos \varphi \end{cases}$$

con $0 \leq \theta \leq 2\pi$, $0 \leq \varphi \leq \pi$.

Se $z \geq 2$, si ha $1 + 2 \cos \varphi \geq 2 \Leftrightarrow$

$$\cos \varphi \geq \frac{1}{2} \Leftrightarrow 0 \leq \varphi \leq \frac{\pi}{3}$$

da cui

$$\Sigma = \begin{cases} x = 2 \cos \theta \sin \varphi \\ y = 1 + 2 \sin \theta \sin \varphi \\ z = 1 + 2 \cos \varphi \end{cases} \quad (\theta, \varphi) \in [0, 2\pi] \times [0, \frac{\pi}{3}]$$

Ne segue

$$m(\Sigma) = \iint_{[0, 2\pi] \times [0, \frac{\pi}{3}]} 4 \sin \varphi \, d\theta \, d\varphi = 8\pi \int_0^{\frac{\pi}{3}} \sin \varphi \, d\varphi = \\ = 4\pi.$$

(ii) Per il teorema del rotore applicato a \underline{F} e Σ , si ha

$$\Phi(\text{rot } \underline{F}, \Sigma) = \oint_{\partial^+ \Sigma} \underline{F} \, ds$$

dove $\partial^+ \Sigma$ è dato da

$$\begin{cases} x^2 + (y-1)^2 + (z-1)^2 = 4 \\ z = 2 \end{cases} \Leftrightarrow$$

$$x^2 + (y-1)^2 = 3, \quad z = 2$$

circonferenza da percorrere nel verso positivo, parametrizzabile da

$$\begin{cases} x(t) = \sqrt{3} \cos t \\ y(t) = \sqrt{3} \sin t + 1 \\ z(t) = 2 \end{cases} \quad t \in [0, 2\pi]$$

Dunque, poiché

$$\underline{F}(x(t), y(t), z(t)) = \begin{pmatrix} 3 \sin^2 t + 1 + 2\sqrt{3} \sin t \\ 3 \cos^2 t + 1 - 2\sqrt{3} \cos t \\ 2\sqrt{3} \cos t (\sqrt{3} \sin t + 1) \end{pmatrix}$$

si ha

$$\begin{aligned} \oint_{\partial^+ \Sigma} \underline{F} \, ds &= \int_0^{2\pi} \left((3 \sin^2 t + 1 + 2\sqrt{3} \sin t) \sqrt{3} \sin t + \right. \\ &+ \left. (3 \cos^2 t + 1 - 2\sqrt{3} \cos t) \sqrt{3} \cos t \right) dt = \\ &= \int_0^{2\pi} (-6 \sin^2 t - 6 \cos^2 t) dt = -12\pi. \end{aligned}$$

E

Es. 2

$$\Phi_\lambda(x, y) = (xy - \arctan(xy), xy^2 + 16\lambda x)$$

$$(i) \quad D_1 \Phi_{\lambda,1}(x, y) = \frac{x^2 y^3}{1 + (xy)^2}, \quad D_1 \Phi_{\lambda,2}(x, y) = y^2 + 16\lambda$$

$$D_2 \Phi_{\lambda,1}(x, y) = \frac{x^3 y^2}{1 + x^2 y^2}, \quad D_2 \Phi_{\lambda,2}(x, y) = 2xy$$

da cui

$$\det J \Phi_\lambda(x, y) = \frac{x^3 y^2 (y^2 - 16\lambda)}{1 + x^2 y^2} = 0 \Leftrightarrow$$

$$(**) \quad x=0 \text{ o } y=0 \text{ o } y = \pm 4\sqrt{\lambda}$$

Affinché B_λ non intersechi una delle rette (*), occorre basta che

$$\begin{cases} 4 \leq 4\sqrt{\lambda} \\ 2\lambda \geq 2 \end{cases} \Leftrightarrow \lambda \geq 1$$

(ii) Si ha

$$|\det J \Phi_\lambda(x, y)| = \frac{(16 - y^2) x^3 y^2}{1 + x^2 y^2}$$

se $2 \leq y \leq 4$, $x \geq 0$. Pertanto

$$\begin{aligned} \iint_{\Phi_\lambda(T)} du \, dv &= \iint_T \frac{(16 - y^2) x^3 y^2}{1 + x^2 y^2} dx \, dy = \\ &= \int_2^4 (16 - y^2) y^2 dy \int_0^{y^{-1}} \frac{x^3}{1 + x^2 y^2} dx = \end{aligned}$$

$$\begin{aligned}
&= \frac{1}{2} \int_2^4 (16-y^2) dy \int_0^{y^{-2}} \frac{y^2 t}{1+y^2 t} dt = \\
&= \frac{1}{2} \int_2^4 (16-y^2) \left[t - \frac{1}{y^2} \log(1+y^2 t) \right]_0^{y^{-2}} dy = \\
&= \frac{1-\log 2}{2} \int_2^4 \frac{16-y^2}{y^2} dy = 1-\log 2.
\end{aligned}$$

Es 3.

(i) La superficie sferica di equazione

$$(x-1)^2 + y^2 + (z-1)^2 = 4$$

si parametrizza

$$\begin{cases}
x = 1 + 2 \cos \theta \sin \varphi \\
y = 2 \sin \theta \sin \varphi \\
z = 1 + 2 \cos \varphi
\end{cases}$$

con $0 \leq \theta \leq 2\pi$, $0 \leq \varphi \leq \pi$.

Se $z \leq 0$ si ha $1 + 2 \cos \varphi \leq 0 \Leftrightarrow$

$$\cos \varphi \leq -\frac{1}{2} \Leftrightarrow \frac{2\pi}{3} \leq \varphi \leq \pi$$

da cui

$$\Sigma = \begin{cases}
x = 1 + 2 \cos \theta \sin \varphi \\
y = 2 \sin \theta \sin \varphi \dots \\
z = 1 + 2 \cos \varphi
\end{cases}$$

con $(\theta, \varphi) \in [0, 2\pi] \times [\frac{2\pi}{3}, \pi]$.

Quindi

$$m(\Sigma) = \iint_{[0, 2\pi] \times [\frac{2\pi}{3}, \pi]} 4 \sin \varphi \, d\theta \, d\varphi = 8\pi \int_{\frac{2\pi}{3}}^{\pi} \sin \varphi \, d\varphi = 4\pi.$$

(ii) Applichiamo il teorema del rotore a F e Σ , osservando che $\partial^+ \Sigma$ è dato da

$$\begin{cases} y^2 + (x-1)^2 = 3 \\ z = 0 \end{cases} \quad \text{che si parametrizza}$$

nel seguente modo

$$\begin{cases} x(t) = \sqrt{3} \cos t + 1 \\ y(t) = \sqrt{3} \sin t \\ z(t) = 0 \end{cases} \quad t \in [0, 2\pi]$$

da cui

$$F(x(t), y(t), z(t)) = (3 \sin^2 t + 1 - 2\sqrt{3} \sin t, 3 \cos^2 t + 1 + 2\sqrt{3} \cos t, 0).$$

Pertanto

$$\begin{aligned} \oint_{\partial^+ \Sigma} F \, ds &= \int_0^{2\pi} ((3 \sin^2 t + 1 - 2\sqrt{3} \sin t) \sqrt{3} \sin t + \\ &+ (3 \cos^2 t + 1 + 2\sqrt{3} \cos t) \sqrt{3} \cos t) \, dt = \\ &= \int_0^{2\pi} (6 \sin^2 t + 6 \cos^2 t) \, dt = 12\pi. \end{aligned}$$