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Some applications of GMT

There are many applications of GMT.
I chose few one close to PDE's and
the Calculus of Variations

- I Lecture { BV functions (quick survey)
SBV functions and Ambrosio's compactness theorem
- II { Approximation of minimal perimeters by scalar Ginzburg-Landau functionals } Γ -convergence
- III & IV { Coarea formula, oriented coarea formula
Jacobian (of Lipschitz maps)
Distributions Jacobian (of Sobolev maps)
Some applications / essential singularities } Currents are needed here!

FIRST LECTURE

Why BV functions....

GENERAL OBSERVATION:

$$u \text{ minimizes } F(u) := \int_{\Omega} f(x, u, \nabla u) dx$$

with Dirichlet boundary condition $u=g$ on $\partial\Omega$

\Downarrow (and \Uparrow if F is convex)

u solves the PDE :

$$\operatorname{div}\left(\frac{\partial F}{\partial p}(x, u, \nabla u)\right) = \frac{\partial F}{\partial u}(x, u, \nabla u)$$

with the Dirichlet bdry cond. $u=g$ on $\partial\Omega$

Example: u minimizes $F(u) := \int_{\Omega} \frac{1}{2} |\nabla u|^2 + fu$ with $u=g$ on $\partial\Omega$

$$\Downarrow$$

$$u \text{ solves } \begin{cases} \Delta u = f & \text{on } \Omega \\ u = g & \text{on } \partial\Omega \end{cases}$$

DIRECT METHODS IN CALC. VAR.

Prove the existence of minimizers of F
 Semicontinuity and compactness arguments
 (and deduce the existence of solutions
 for the Euler-Lagrange eq. associated
 to F).

Dirichlet (principle), Hilbert, Tonelli.

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In other words, we want to argue as follows:

Let F be a lower semicontinuous function (a!) on a topological space X , and assume that the sublevels of F (the sets $\{u \in X : F(u) \leq c\}$) are sequentially (pre)compact.

Then every minimizing sequence (u_n) (that is (u_n) satisfies $F(u_n) \rightarrow \inf_{u \in X} F(u)$) admits a converging subsequence (u_{n_k}) and the limit is a minimizer of F .

Example

$$F(u) := \int_{\Omega} \frac{1}{2} |\nabla u|^2 + fu \quad \text{is lower semicontinuous}$$

$$\text{on } X := \{u \in W^{1,2}(\Omega) : u=g \text{ on } \partial\Omega\}$$

w.r.t. the weak topology.

Sublevels of F are bounded and weak-closed in $W^{1,2}$, and therefore sequentially compact

We need to use Sobolev spaces such as $W^{1,2}$!

Question:

What about $F(u) := \int_{\Omega} \sqrt{1 + |\nabla u|^2}$?

area of the graph of u

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BV functions

Def.: $BV(\Omega) := \left\{ u \in L^1(\Omega) : \begin{array}{c} Du \text{ is a bounded measure} \\ \uparrow \\ \text{distributional gradient} \end{array} \right\}$

in other words there exists

real measures μ_i s.t.

$$\int_{\Omega} \frac{\partial \phi}{\partial x_i} u = - \int_{\Omega} \phi d\mu_i \quad \text{for } i=1, \dots, n$$

$\Omega \quad \Omega \quad \phi \in C_c^1(\Omega)$

and $Du = \left(\frac{\partial u}{\partial x_1}, \dots, \frac{\partial u}{\partial x_n} \right) = (\mu_1, \dots, \mu_n)$

$$\|u\|_{BV} := \|u\|_1 + \|Du\|$$

total variation of Du
(as a vector measure)

Basic Compactness

If $\|u_n\|_{BV} \leq c < +\infty$

then there exists a subseq. (u_{n_k}) converging to $u \in BV$ in the following sense:

$$\left\{ \begin{array}{l} u_n \rightarrow u \text{ in } L^1(\Omega) \\ Du_n \rightarrow Du \text{ in the weak* topology of measures} \end{array} \right.$$

(This is called weak (weak*) convergence in BV)

PROOF:

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Useful tools

(Ω bounded regular domain)

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o $BV(\Omega) \hookrightarrow L^p(\Omega)$ for every $p \leq \frac{n}{n-1}$

(the immersion is compact
for $p < \frac{n}{n-1}$)

o $T : BV(\Omega) \rightarrow L^1(\partial\Omega)$ Trace operator

$$(T : u \mapsto u|_{\partial\Omega})$$

o $\|u - \bar{u}\|_p \leq C_{p,n} \|Du\| \quad \forall p \leq \frac{n}{n-1}$

average
of u on Ω

Poincaré inequality

$\|Du\| + |\bar{u}|$

$$\left. \begin{array}{l} \|Du\| + \|Tu\|_{L^1(\partial\Omega)} \\ \vdots \end{array} \right\}$$

are equivalent to
the standard norm
of BV

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Set of finite perimeter

Def. $E \subset \mathbb{R}^n$ has finite perimeter in \mathbb{R}^n
if $1_E \in BV(\mathbb{R}^n)$
and we set
 $\text{Per}_{\mathbb{R}^n}(E) := \|D1_E\|$

Motivation: if ∂E is of class C^1 , or even Lipschitz it is easy to see that

$$1_E \in BV(\mathbb{R}^n) \text{ and } D1_E = \nu_{\partial E} \cdot H^{n-1} L(\partial E \cap \mathbb{R}^n)$$

Hence

$$\begin{aligned} \text{Per}_{\mathbb{R}^n}(E) &:= \|D1_E\| \\ &= H^{n-1}(\partial E \cap \mathbb{R}^n) \end{aligned}$$

Basic compactness (and semicontinuity)

E_n seq. of finite perimeter sets in \mathbb{R}^n

If $\text{Per}_{\mathbb{R}^n}(E_n) \leq c < +\infty$

Then E_n converge up to subseq. to E in the L^1 sense ($1_{E_n} \rightarrow 1_E$ in $L^1 \Leftrightarrow \mathcal{E}(E_n, \Delta E) \rightarrow 0$)

Moreover $\text{Per}_{\mathbb{R}^n}(E) \leq \liminf_n \text{Per}_{\mathbb{R}^n}(E_n)$

Corollary: existence of sets with minimal perimeter....

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Fine structure of BV functions

- $u \in BV(\mathbb{R}^n)$ is approximately differentiable (in the L^1 -sense) at \mathbb{R}^n a.e. $x \in \mathbb{R}^n$

there exists $\nabla u(x)$ s.t.

$$\lim_{r \rightarrow 0} \int_{|t| \leq r} \frac{|u(x+t) - u(x) - \nabla u(x) \cdot t|}{|t|} dt = 0$$

- u admits an approximate limit (in the L^1 -sense) $\tilde{u}(x)$ at every x except a singular set S_u which is H^{n-1} σ -finite

- S_u is rectifiable, (countably $(H^{n-1}, n-1)$ -rectifiable) that is, it can be covered by countably many C^1 -hypersurfaces (except an H^{n-1} negligible subset).

In particular S_u admits a normal ν_{S_u}

- For H^{n-1} a.e. $x \in S_u$, there exists the approximate limits $u^+(x)$ and $u^-(x)$ on the two sides of S_u

o

$$\begin{aligned} Du &= \underbrace{\nabla u \cdot \mathcal{L}^n}_{\text{a.c. part of } Du} + \underbrace{(u^+ - u^-) \nu_{S_u} \cdot H^{n-1} L_{S_u}}_{\text{"Jump" part of } Du} + \underbrace{D_C u}_{\text{"Cantor part}} \\ (\quad) & \quad (D1_E = \nu_{\partial^* E} \cdot H^{n-1} L_{\partial^* E}) \end{aligned}$$

SBV functions

$$Du = \nabla u \cdot \mathcal{L}_n + (u^+ - u^-) \nu_{S_u} \cdot H^{n-1}|_{S_u}$$

Def. $SBV(\Omega) := \left\{ u \in BV(\Omega) : D_c u = 0 \right\}$

SBV compactness (L. Ambrosio)

Let (u_n) be a sequence in $SBV(\Omega)$ s.t.:

- o $\|u_n\|_{BV} \leq C < +\infty$
- o ∇u_n are equiintegrable
(i.e. $\int f(|\nabla u_n|) \leq C < +\infty$ for some
 $f: \mathbb{R}^+ \rightarrow \mathbb{R}^+$ such that $\frac{f(t)}{t} \rightarrow +\infty$ as $t \rightarrow +\infty$)
- o $H^{n-1}(S_{u_n}) \leq C < +\infty$.

Then u_n converge, up to subseq., to

some $u \in SBV$.

Moreover

- o $\nabla u_n \rightarrow \nabla u$ weakly in L^1
- o $(Du_n)_s \rightarrow (Du)_s$ in the sense of measures

$$(u_n^+ - u_n^-) \nu_{S_{u_n}} \cdot H^{n-1}|_{S_{u_n}}$$

?

Application: existence of minimizers
for the Mumford-Shah functional

$$F(u) := \int_{\Omega \setminus S_u} |\nabla u|^2 + \alpha H^{n-1}(S_u) + \beta \int_{\Omega} |u - g|^2$$

where $g: \Omega \rightarrow [0,1]$ is given

and u is assumed \mathcal{C}^1 out of a closed singular set S_u which is H^{n-1} -finite

↑ ↗ not prescribed!

arising in image segmentation problems

(but similar functionals appears in
other problems ...)

Direct proof in dimension $n=2$

[Mumford-Shah, De Giorgi-Moser-Solimini]

Proof by direct methods + regularity theory

EXISTENCE OF MINIMIZERS } L. Ambrosio
IN $SBV(\Omega)$

Regularity theory: minimizers } De Giorgi-
are C^1 outside a closed } -Carriero-Leaci
singular set S_u

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Proof of Ambrosio's theorem

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for $n=1$ is trivial

u_n converge (up to subseq.) to some $u \in BV$

$$\begin{aligned} D u_n &= \nabla u_n \cdot \mathcal{L}^1 + \sum_{i=1}^N \alpha_i \delta_{x_i} \quad N \text{ independent} \\ &\quad \downarrow \mathcal{H}^{n-1} \quad \downarrow L^1 \quad \downarrow \mathcal{H}^{n-1} \\ Du &= g \cdot \mathcal{L}^1 + \sum_{i=1}^N \alpha_i \delta_{x_i} \end{aligned}$$

Hence $u \in SBV$, $g = \nabla u$, (and $\nabla u_n \rightarrow \nabla u$).

Not as simple in dimension $n > 1$!

Lemma (Chain rule).

If $u \in BV(\mathbb{R})$, $\varphi: \mathbb{R} \rightarrow \mathbb{R}$ is C^1 and Lipschitz
then $\varphi(u) \in BV$ [easy....]

and

$$\begin{aligned} D(\varphi(u)) &= \dot{\varphi}(u) (\nabla u \cdot \mathcal{L}^n + D_C u) \\ &\quad + (\varphi(u^+) - \varphi(u^-)) \nu_{S_u} \cdot \mathcal{H}^{n-1} L S_u \end{aligned}$$

Characterization of SBV

Given $u \in BV$, then

$$u \in SBV \iff \exists g \in L^1 \text{ s.t. } \sup_{0 \leq \varphi \leq 1} \|D(\varphi(u)) - \dot{\varphi}(u) g \cdot \mathcal{L}^n\| < +\infty$$

And if so, $g = \nabla u$.

Proof:

Lemma (the theorem follows...)

Let (u_n) be bounded in BV , $u_n \in SBV$ and

$$u_n \rightarrow u \in BV;$$

Assume $\nabla u_n \rightarrow g$ weakly in L^1 ;

$$\text{Assume } \mathcal{H}^{n-1}(S_{u_n}) \leq C < +\infty.$$

Then $u \in SBV$ and $g = \nabla u$.

Proof

It suffices to show that

$$\|D(\varphi(u)) - \dot{\varphi}(u) g \cdot \mathcal{L}^n\| \text{ is bounded for all } 0 \leq \varphi \leq 1$$

$$\begin{array}{ccc} \uparrow & & \uparrow \\ D\varphi(u_n) & & \dot{\varphi}(u_n) \cdot \nabla u_n \cdot \mathcal{L}^n \end{array}$$

Hence

$$\begin{aligned} &\|D(\varphi(u)) - \dot{\varphi}(u) g \cdot \mathcal{L}^n\| \\ &\leq \liminf \|D(\varphi(u_n)) - \dot{\varphi}(u_n) \nabla u_n \cdot \mathcal{L}^n\| \\ &\leq \liminf \|(\varphi(u_n^+) - \varphi(u_n^-)) \nu_{S_{u_n}} \cdot \mathcal{H}^{n-1} L S_{u_n}\| \\ &\leq \liminf \mathcal{H}^{n-1}(S_{u_n}) \\ &\leq C < +\infty. \end{aligned}$$

Approximation of perimeter by scalar Ginzburg-Landau functionals

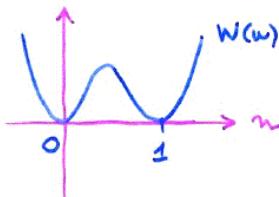
[Problem : asymptotic behaviour as $\varepsilon \rightarrow 0$
of minimizers of]

$$F_\varepsilon(u) := \int_{\Sigma} |\nabla u|^2 + \frac{1}{\varepsilon^2} W(u)$$

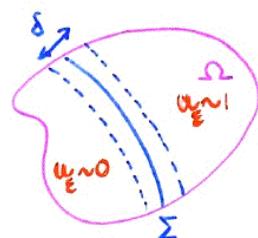
Scalar G.-L.
functionals
(a.k.a. Cahn-Hilliard)
appears in
phase separation
models ...

with prescribed average

$$\int_{\Sigma} u = m, \quad 0 < m < 1$$



Heuristic



Assume u_ε is as in the picture. Then

$$F_\varepsilon(u_\varepsilon) \sim H^{n-1}(\Sigma) S \left(\frac{1}{\delta^2} + \frac{1}{\varepsilon^2} \right)$$

$$\sim \frac{1}{\varepsilon} H^{n-1}(\Sigma)$$

optimization
of S gives
 $\delta \sim \varepsilon$

We expect $u \approx 1$ or 0 everywhere outside
an ε -neighbourhood of a minimal
surface Σ

(chosen among those that separate Σ into a
region of volume $m|\Sigma|$ and one of vol. $(1-m)|\Sigma|$)

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you can do better ...

Ansatz : $u_\varepsilon(x) := \gamma \left(\frac{\text{dist}_\Sigma(x)}{\varepsilon} \right)$ $\gamma: \mathbb{R} \rightarrow [0, 1]$

Then : $F_\varepsilon(u) := \frac{1}{\varepsilon} H^{n-1}(\Sigma) \int_{-\infty}^{\infty} \dot{\gamma}^2 + W(\gamma)$

$\cong \frac{1}{\varepsilon} S H^{n-1}(\Sigma)$ where $S := 2 \int_0^1 W(u)$
after optimization
of γ

Can we make such statements rigorous?
(possibly without working too hard)

Γ -convergence (in one slide...)

X metric space (cluster : a space of functions)

$$F_\varepsilon : X \rightarrow [0, +\infty]$$

Def. We say that F_ε Γ -converge to F on X if:

$$(i) \quad \forall u \in X \quad \forall u_\varepsilon \rightarrow u \quad F(u) \leq \liminf_{\varepsilon \rightarrow 0} F_\varepsilon(u_\varepsilon)$$

$$(ii) \quad \forall u \in X \quad \exists u_\varepsilon \rightarrow u \quad F(u) = \lim_{\varepsilon \rightarrow 0} F_\varepsilon(u_\varepsilon)$$

Definition due to DeGiorgi-Franzoni (on topological spaces)

It is actually KURATOWSKI convergence of the epigraphs $E_\varepsilon := \{(u, t) \in X \times [0, +\infty] : F_\varepsilon(u) \leq t\}$

Main property:

If u_ε minimizes F_ε on X , then every limit point u of (u_ε) is a minimizer of F

Also:

If $F_\varepsilon \xrightarrow{\Gamma} F$ and $G : X \rightarrow [0, +\infty]$ is continuous then $F_\varepsilon + G \xrightarrow{\Gamma} F + G$ (stability under cont. perturbations)

[FINDING THE Γ -LIMIT OF F_ε GIVES INFO ABOUT THE LIMIT OF MINIMIZ. u_ε]

Provided that:

(a) F is not constant!

(b) (u_ε) is pre-compact in X !

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Back to the original problem

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Theorem (Modica-Mortola (77), Modica (87))

Fix $m \in (0, 1)$, let $X := \{u \in L^1(\Omega) : f_\Omega u = m\}$

Then

$$F_\varepsilon(u) := \begin{cases} \int_{\Omega} \varepsilon |\nabla u|^2 + \frac{1}{\varepsilon} W(u) & \text{for } u \in W^{1,2} \\ +\infty & \text{elsewhere in } X \end{cases}$$

$\downarrow \Gamma$

$$F(u) := \begin{cases} \varepsilon \|Du\| = \varepsilon H^{m-1}(\partial u) & \text{for } u \in BV(\Omega; \{0, 1\}) \\ +\infty & \text{elsewhere in } X. \end{cases}$$

Moreover every sequence (u_ε) s.t. $F_\varepsilon(u_\varepsilon) \leq C < \infty$ is precompact in X

Corollary

If u_ε minimizes F_ε , then u_ε converge, (up to subseq.) to $u = \mathbf{1}_E$ where E minimizes the perimeter among all sets in Ω with measure $m(\Omega)$.

Something better can be done

Proof

Compactness: $F_\varepsilon(u_\varepsilon) \leq C < +\infty \Rightarrow (u_\varepsilon)$ precomp. in L^1

$$F_\varepsilon(u) = \int_{\Omega} \varepsilon |\nabla u|^2 + \frac{1}{\varepsilon} W(u)$$

$$\begin{aligned} &\geq \int_{\Omega} 2\sqrt{W(u)} |\nabla u| \\ \text{with } a^2 + b^2 &\geq 2ab \\ a := \sqrt{\varepsilon |\nabla u|^2} & \\ b := \sqrt{W(u)/\varepsilon} & \end{aligned}$$

$$\begin{aligned} &= \int_{\Omega} |\mathcal{D}(H(u))| = \|\mathcal{D}(H(u))\| \\ \text{here } H' &= 2\sqrt{W} \end{aligned}$$

$$\text{Hence: } C \geq F_\varepsilon(u_\varepsilon) \geq \int_{\Omega} |\mathcal{D}(H(u_\varepsilon))| = \|\mathcal{D}(H(u_\varepsilon))\|$$

$\Rightarrow H(u_\varepsilon)$ is precompact in L^1

$\Rightarrow u_\varepsilon$ is precompact in L^1

Lower bound: $u_\varepsilon \rightarrow u \Rightarrow F(u) \leq \liminf_{\varepsilon \rightarrow 0} F_\varepsilon(u_\varepsilon)$

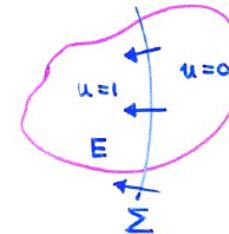
$H(u_\varepsilon) \rightharpoonup H(u)$ in BV weak*

Hence:

$$\begin{aligned} \liminf F_\varepsilon(u_\varepsilon) &\geq \liminf \|\mathcal{D}(H(u_\varepsilon))\| \\ &\geq \|\mathcal{D}(H(u))\| \\ &= \varepsilon H^{n-1}(Su) = \varepsilon \|Du\| \end{aligned}$$

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Upper bound: $\forall u \exists u_\varepsilon \rightarrow u, F_\varepsilon(u_\varepsilon) \geq F(u)$



We can assume
 $u = 1_E$, E smooth

Let $d_\Sigma(x) :=$ oriented distance
from $\partial E = \Sigma$

$$\text{Set } u_\varepsilon(x) := \gamma \left(\frac{d_\Sigma(x)}{\varepsilon} \right)$$

where γ solves the ODE $\begin{cases} \dot{\gamma} = 2\sqrt{W(\gamma)} \\ \gamma(0) = 1/2 \end{cases}$

Indeed for such u_ε there holds

$$\begin{aligned} F_\varepsilon(u_\varepsilon) &= \int_{\Omega} \varepsilon |\nabla u_\varepsilon|^2 + \frac{1}{\varepsilon} W(u_\varepsilon) \\ &\leq H^{n-1}(\Sigma) \int_{-\infty}^{\infty} \varepsilon \dot{\gamma}^2 + \frac{1}{\varepsilon} W(\gamma) d\gamma \\ &= H^{n-1}(\Sigma) \int_{-\infty}^{\infty} 2\sqrt{W(\gamma)} |\dot{\gamma}| d\gamma \\ &= H^{n-1}(\Sigma) \int_0^1 H(r) dr \\ &= H^{n-1}(\Sigma) \cdot \varepsilon \end{aligned}$$

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JACOBIANS OF LIPSCHITZ MAPS

Area formula

$u: \mathbb{R}^n \rightarrow \mathbb{R}^k$ Lipschitz, $n \geq k$.

Then for every $A \subset \mathbb{R}^n$

$$\int_{\mathbb{R}^k} \mathcal{H}^{n-k} (\bar{u}(y) \cap A) dy = \int_A p(x) dx$$

where $p(x) = \sqrt{\det[(D_u(x))(D_u(x))^t]}$

$$\begin{aligned} \text{KxK minor of } (D_u(x)) &= \sqrt{\sum_M (\det M)^2} \\ &= |du_1 \wedge \dots \wedge du_k| \\ &\quad \text{components of } u \\ &\quad \left[\text{Recall that } df = \sum_i \frac{\partial f}{\partial x_i} dx_i \right] \\ &= |u^\#(dy_1 \wedge \dots \wedge dy_k)| \\ &\quad \text{pull back according to } u \\ &\quad \text{of } dy_1 \wedge \dots \wedge dy_n, \\ &\quad \text{standard (volume) form on } \mathbb{R}^k \end{aligned}$$

Def

We call k -dimensional Jacobian of $u: \mathbb{R}^n \rightarrow \mathbb{R}^k$ the k -form

$$Ju := du_1 \wedge \dots \wedge du_k$$

$$= u^\#(dy_1 \wedge \dots \wedge dy_k)$$

ATTENTION: usually the word "Jacobian" is used for $|Ju|$. This notation (and definition) is not widely used!

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Identification of vectors and covectors

Def.

$$\star : \Lambda^k(\mathbb{R}^n) \rightarrow \Lambda_{n-k}(\mathbb{R}^n)$$

$$\star : dx_{\underline{i}} \mapsto \epsilon(\underline{i}, \underline{i}) e_{\underline{i}}$$

\uparrow
multi-index
 (i_1, \dots, i_k)

\uparrow
complement to
the multi-index

\uparrow
sign of the permutation
that re-orders $(\underline{i}, \underline{i})$

\star is a (sort of) Hodge operator, identifying k -covectors and $(n-k)$ -vectors.

Hence, if ω is a k -form,
then $\star \omega$ is a $(n-k)$ -current.

\star behaves nicely w.r.t. ∂ and d

$$\star(d\omega) = (-1)^{n-k} \partial(\star\omega)$$

ATTENTION
this is not
the standard
Hodge op.

Geometrically:

If $\omega = \omega_1 \wedge \omega_2 \wedge \dots \wedge \omega_k$ is a simple form
then $\star \omega$ is a simple vector that
spans the $(n-k)$ -space $(\ker \omega_1) \cap (\ker \omega_2) \cap \dots \cap (\ker \omega_k)$

More on the Coarea formula

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If $u: \mathbb{R}^n \rightarrow \mathbb{R}^k$ Lipschitz

$$\left\{ \begin{array}{l} \text{Then } \int_{\mathbb{R}^k} \mathcal{H}^{n-k}(\bar{u}(y) \cap A) dy = \int_A |\nabla u| dx \quad \forall A \subset \mathbb{R}^n \end{array} \right.$$

Hence $\bar{u}(y)$ is \mathcal{H}^{n-k} -locally finite for \mathcal{H}^k -a.e. y .

Moreover $\bar{u}(y)$ is $(n-k)$ -rectifiable. [Fed]....

The result is non trivial even for u of class C^1 (cf. Sard's lemma).

Moreover $\star J_u(x) := \frac{\star J_u(x)}{|J_u(x)|}$
 is a simple $(n-k)$ -vector that orients $Tan(\bar{u}(y), x)$
 for \mathcal{H}^{n-k} -a.e. $x \in \bar{u}(y)$ and \mathcal{H}^k -a.e. y .

Hence we set $N_y = N_y(u) = [\bar{u}(y), \star, 1]$
 oriented level curve
 of u ...

In particular we have the oriented coarea form.:

$$\int_{\mathbb{R}^k} N_y dy = \star J_u \mathcal{L}^n$$

What about the boundary of N_y ?

Simple cases

if $n=k$ then

$$u: \mathbb{R}^k \rightarrow \mathbb{R}^k$$

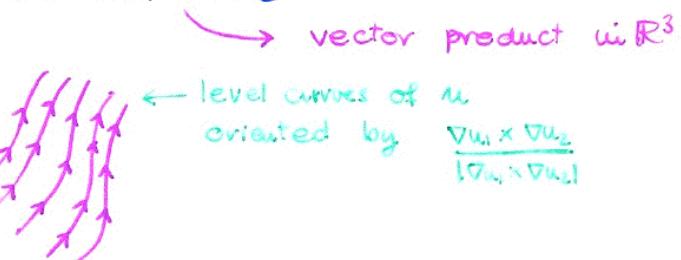
$$Ju = (\det(\nabla u(x))) dx_1 \wedge \dots \wedge dx_k$$

$$\star Ju = \det(\nabla u(x)) \cdot \mathcal{L}^k$$

if $n=3, k=2$ then

$$u: \mathbb{R}^3 \rightarrow \mathbb{R}^2, \quad u = (u_1, u_2)$$

$$\star Ju = \nabla u_1 \times \nabla u_2$$



The oriented coarea formula says that the "diffuse" 1-current $\star Ju = (\nabla u_1 \times \nabla u_2) \cdot \mathcal{L}^3$ can be decomposed as integral of the 1-currents associated to the level curves.

if $k=1$ then

$$u: \mathbb{R}^n \rightarrow \mathbb{R}$$

$$Ju = du = (\nabla u)^*$$

$\frac{\nabla u}{|\nabla u|}$ orients (as a normal) the level surfaces of u

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Beyond Lipschitz maps: Jacobian of Sobolev maps

Recall

$$W^{1,p}(\Omega; \mathbb{R}^k) := \left\{ u \in L^p(\Omega; \mathbb{R}^k) : Du \in L^p(\Omega, \Lambda^k(\mathbb{R}^n)) \right\}$$

distributional derivative

Question: for which p can we define the jacobian of $W^{1,p}$ maps?

Answer: everything is fine for $p \geq k$

$$\begin{aligned} J : W^{1,p}(\Omega; \mathbb{R}^k) &\rightarrow L^{p/k}(\Omega; \Lambda^k(\mathbb{R}^n)) \\ u &\mapsto Ju \end{aligned}$$

is a continuous operator

But there holds more: J is sequentially continuous from $W^{1,p}$ -weak to $L^{p/k}$ -weak (for $p > k$)

Important, and non obvious!

What about $W^{1,p}$ with $p < k$?

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Fundamental identity

for u of class C^2

$$Ju = du_{n-k+1} \wedge \dots \wedge du_k = \frac{1}{k} d \left(\sum_{i=1}^k (-1)^{i-1} u_i \wedge du_j \right)$$

that is to say

very "popular",
in the case
 $n=k$

$$du = u^\# (dy_1 \wedge \dots \wedge dy_k) = \frac{1}{k} d \left(u^\# \left(\sum_{i=1}^k (-1)^{i-1} y_i \wedge dy_j \right) \right)$$

standard volume form on \mathbb{R}^k
(k -1) form on \mathbb{R}^k

standard volume form on every sphere centered at 0.

COROLLARY: ★ Ju is a boundary
(precisely ★ $Ju = (-1)^{n-k+1} \partial(\star Ju)$)

DEFINITION (Ball, Brezis-Coron-Lieb, JERRARD-SONER)

For every u in $W^{1,k-1}(\Omega; \mathbb{R}^k)$ we set

$$Ju := \frac{1}{k} d \left(\sum_{i=1}^k (-1)^{i-1} u_i \wedge du_j \right)$$

J is (sequentially) continuous from $W^{1,k-1} L^\infty$ in $D'(\Omega, \Lambda^k(\mathbb{R}^n))$

More precisely, if

u_n are uniformly bounded and

$u_n \rightarrow u$ weakly in $W^{1,p}$ for some $p > k-1$
strongly in $W^{1,k-1}$

then

$Ju_n \rightarrow Ju$ in the sense of distributions

$\star Ju_n \rightarrow \star Ju$ in the sense of currents

Remark: If the pointwise and the distributional Jacobian are both defined (in $W^{1,k-1} L^\infty$) then they agree.

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Jacobian and the area formula for Sobolev maps

Let $u \in W^{1,k}(\mathbb{R}; \mathbb{R}^k)$

Let \mathcal{D}_u be the set of approximate differentiability. Then

$$\int_{\mathbb{R}^k} H^{k-k}(\tilde{u}(y) \cap \mathcal{D}_u) dy = \int_{\mathbb{R}^n} |\mathbf{J}u(x)| dx \leq \|\nabla u\|_k < +\infty$$

Moreover $\tilde{u}(y) \cap \mathcal{D}_u$ is rectifiable and oriented by $\frac{\star J_u}{|\nabla u|} =: \tau$ for a.e. y .

Thus $N_y := [\tilde{u}(y) \cap \mathcal{D}_u; \tau; \{ \}]$ is a rectif. current and

$$\int_{\mathbb{R}^k} N_y dy = \star J_u$$

Proof: \mathcal{D}_u can be covered by sets where u agrees with a Lipschitz map (countably many...)

Question: DO WE HAVE TO THROW AWAY \mathcal{D}_u ?

See: Maly-Swanson-Ziemer

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JACOBIAN OF MAPS VALUED IN SPHERES

from now on we assume $u: \mathbb{R} \subset \mathbb{R}^n \rightarrow S^{k-1} \subset \mathbb{R}^k$

If $u \in W^{1,k}(\mathbb{R}; S^{k-1})$ then $J_u = 0$

for a.e. x , du_1, \dots, du_k are linearly dependent because $du: \mathbb{R}^n \rightarrow \text{Tan}(S^{k-1}, u(x))$ and the latter has dimension $< k$.

This may not be true if $u \in W^{1,p}$ with $k \leq p < \infty$

Fundamental example:

$$u: \mathbb{R}^k \rightarrow S^{k-1}; \quad u(x) := \frac{x}{|x|} \quad (\text{then } u \in W^{1,p} \forall p < \infty)$$

then $\star J_u := \frac{\alpha_k}{V} \delta_0 \leftarrow \begin{array}{l} \text{Dirac mass at 0,} \\ \downarrow \\ \text{Volume of unit ball in } \mathbb{R}^k. \end{array}$

Proof

Approximate u by $u_\epsilon := \begin{cases} \frac{x}{\epsilon} & \text{if } |x| < \epsilon \\ \frac{x}{|x|} & \text{if } |x| \geq \epsilon \end{cases}$

$$\text{Then } \star J_{u_\epsilon}(x) = \frac{1}{\epsilon^k} \mathbf{1}_{B(0, \epsilon)}$$

and $\star J_{u_\epsilon} \rightarrow \star J_u$ in the sense of currents...

Important

$\underbrace{J_u}_{\substack{\text{distributional} \\ \text{definition}}} \neq \underbrace{\mathbf{d}u_1 \wedge \dots \wedge \mathbf{d}u_k}_{\substack{\text{pointwise} \\ \text{definition} \\ = 0 \text{ in this case}}} !$

Jacobian of maps with "nice" singularities

CASE $n=k$

Given $u: \mathbb{R}^k \rightarrow S^{k-1}$ smooth outside a finite singular set $S = \{x_i\}$, then

$$\star Ju = \alpha_k \sum_i d_i \delta_{x_i}$$

$$d_i := \deg(u, \partial B_i, S^{k-1})$$

where B_i is a ball that contains x_i only ... it does not matter which ball!

Proof: Of course, $\star Ju$ is supported in $S = \{x_i\}$!

Let ρ be a smooth radial function centered at some x_i , null on the others

$$\begin{aligned} \int_{\mathbb{R}^k} \star Ju \rho dx &= \int_{\mathbb{R}^k} (\rho Ju) \cdot e_1 \wedge \dots \wedge e_k \\ &= \int_{\mathbb{R}^k} -d\rho \wedge \frac{1}{k} Ju \\ &= \int_0^\infty -\dot{\rho}(t) \left(\int_{tS^{k-1}} \frac{1}{k} Ju \right) dt \quad \text{acting on } z \text{ tangent to } tS^{k-1} \\ &= \int_0^\infty -\dot{\rho}(t) \frac{1}{k} d_i \text{ vol}(S^{k-1}) \text{ at } x_i \text{ with radius } t \\ &= \rho(0) d_i \omega_k \end{aligned}$$

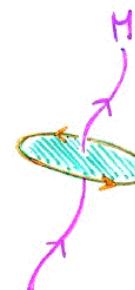
(25)

Jacobian of maps with nice singularities
CASE $m > k$

Given $u: \mathbb{R}^n \rightarrow S^{k-1}$ smooth outside an ORIENTED manifold M without boundary and with codimension k in \mathbb{R}^n . then

$$\star Ju = \alpha_k [M, \varepsilon_M, \theta] \quad \text{orientation of } M.$$

where the multiplicity $\theta(x)$ at $x \in M$ is given by



$$\theta(x) := \deg(u, \partial E, S^{k-1})$$

E $n-k$ dimensional disc (suitably oriented)
transversal to M
intersecting M at x only

θ is locally constant (cf. $\star Ju$ has no bdry).

No proof will be given for this formula....
(it follows from the case $n=k$ by slicing techniques).

COMMENT

We might say that $\star Ju$ captures the "essential singularity of u !"

$\star Ju$ is sometimes called "topological singularity" of u [Riviere, Pakzad,...]

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FOURTH LECTURE

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What can be said about Jacobians of generic Sobolev maps?

THEOR. Let $u \in W^{k+1}(\Omega; S^{k-1})$

o Then

$$\star Ju = \alpha_k \partial N$$

where N is an $(n-k+1)$ -rectifiable current with integer multiplicity.

o More precisely

$$\star Ju = (-1)^{n-k+1} \alpha_k \partial N_y \quad \text{for a.e. } y \in S^{k-1}$$

COROLLARY

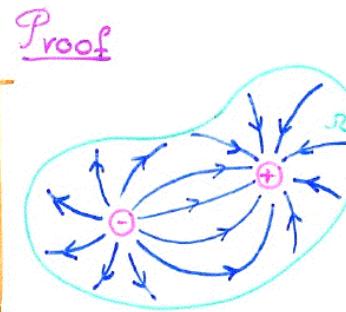
- o If $\star Ju$ is a measure, it is also an $(n-k)$ -dimensional integral current (up to α_k)
- o In particular, for $n=k$, $\star Ju$ is a finite sum of Dirac Masses!

Brezis-Coron-Lieb for $n=k$
Jerrard-Soner for $n < k$

simple proof: G.A.-Baldo-Orlandi (see also Hang-Lin)

i.e. has finite mass!

PROOF BY PICTURE!



level curves
of $u: \Omega \rightarrow S^1$



singularities of u
(where Ju is sitting)

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Can we turn this picture into a real proof?

$$\text{Since } Ju := \frac{1}{k} d(Ju) = \frac{1}{k} d(u^\# \tilde{\omega}) \quad \sum_{i=1}^k (-1)^{i-1} y_i \alpha_k dy_i$$

$$\text{Then } \star Ju = \frac{(-1)^{n-k+1}}{k} \partial(\star Ju) = \frac{(-1)^{n-k+1}}{k} \int_{y \in S^{k-1}} \partial N_y \, dH^{k-1}(y)$$

This is not enough.

We claim indeed that more holds: given $p: S^{k-1} \rightarrow \mathbb{R}$
such that $\int_{S^{k-1}} p = 1$ then

$$Ju = \frac{1}{k} d(Ju) = \frac{1}{k} d(u^\# \tilde{\omega}) = \frac{1}{k} d(u^\# (p \tilde{\omega}))$$

Hence

$$\star Ju = \frac{(-1)^{n-k+1}}{k} \int_{y \in S^{k-1}} p(y) \partial N_y \, dH^{k-1}(y)$$

and taking a sequence $p \rightarrow k \alpha_k \delta_{\bar{y}}$

$$\star Ju = \frac{(-1)^{n-k+1}}{k} k \alpha_k \partial N_{\bar{y}} = (-1)^{n-k+1} \alpha_k \partial N_{\bar{y}}$$

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(FEW) APPLICATIONS

It remains to prove the claim

$$d(u^*\tilde{\omega}) = d(u^*(\rho\tilde{\omega}))$$

where $\tilde{\omega}$ is the standard volume form on S^{k-1} , and ρ is a function on S^{k-1} s.t. $\int_{S^{k-1}} \rho = 1$, and $u \in W^{1,k-1}(\mathbb{S}^k, S^{k-1})$

That is, we must show that the following form is null:

$$\begin{aligned} & d(u^*\tilde{\omega}) - d(u^*(\rho\tilde{\omega})) \\ &= d(u^*\tilde{\omega} - u^*(\rho\tilde{\omega})) \\ &= d(u^*((1-\rho)\tilde{\omega})) \end{aligned}$$



$$\begin{aligned} & \text{But } (1-\rho)\tilde{\omega} \text{ is exact, that is } \frac{(1-\rho)\tilde{\omega} = d\alpha}{\text{ON } S^{k-1}} \\ &= d(u^*(d\alpha)) \\ &= d(d(u^*\alpha)) \\ &= 0 \end{aligned}$$

Follows by the fact that $(k-1)$ -th cohomology group of S^{k-1} (and of any connected $(k-1)$ -dim manifold) is \mathbb{R} , and the identification is given by the integral....

ALTERNATIVE (FALSE!) PROOF:

$$d(u^*((1-\rho)\tilde{\omega})) = u^*(d((1-\rho)\tilde{\omega})) = u^*(0) = 0$$

Why is it false?
FIRST IDENTITY REQUIRES $u \in W^{1,k}$!



the differential of a $(k-1)$ -form on any $(k-1)$ -dimensional manifold must be 0.

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Lifting Sobolev maps

Let $u: \mathbb{S}^k \rightarrow S^1$, $u \in W^{1,p}$ ($p \geq 1$)
Is there $\Theta: \mathbb{S}^k \rightarrow \mathbb{R}$, $\Theta \in W^{1,p}$
such that
 $e^{2\pi i \Theta} = u$?

This is known as "lifting problem", see
Demengel, Bourgain-Brezis-Mironescu, others...

[Solving this problem implies a solution
of the approximation problem:

Let $u: \mathbb{S}^k \rightarrow S^1$, $u \in W^{1,p}$

[Is there $u_n: \mathbb{S}^k \rightarrow S^1$, u_n of class C^1 (or C^∞)
s.t. $u_n \rightarrow u$ in norm ?]

Answer:

If u can be lifted, then $J_u = 0$.

The converse is true when \mathbb{S}^k is simply connected.

In particular there is always lifting
(and approximation) for $p \geq 2$.

The case $p > k$ would have been trivial.

THE PROOF IS SIMPLE, AND WILL BE GIVEN...

Preliminary observation

Every $u \in W^{1,p}(\mathbb{S}, S^1)$ can be written as

$$u = e^{2\pi i \theta}$$

with $\theta \in W^{1,p}(\mathbb{S}, \mathbb{R}/\mathbb{Z})$ Nothing deep:
we have just changed
the representation of S^1

More precisely

$$2\pi d\theta = u_1 du_2 - u_2 du_1 = -i \bar{u} du$$

and since $|u|=1$

$$2\pi |\nabla \theta| = |\nabla u|$$

Moreover $2\pi d\theta = Ju$ hence $\pi d(d\theta) = Ju$

is not 0 because θ
is NOT a zero-form
(it is not valued in \mathbb{R})

PROOF OF THE THEOREM.

If $u = e^{2\pi i \theta}$ with $\theta \in W^{1,p}(\mathbb{S}, \mathbb{R})$

Then $Ju = \pi d(d\theta) = 0$. valued in \mathbb{R}

On the other hand, $Ju=0$ implies that the 1-form $d\theta$ is exact, that is $d\theta = d\tilde{\theta}$ for some \mathbb{R} -valued $\tilde{\theta}$.

Up to some constant, $\tilde{\theta}$ provides the lifting of u .

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Remarks

The problem of Lifting has been studied by Bourgain, Brezis, Mironescu in particular for maps in fractional Sobolev spaces of maps from $\mathbb{S} \rightarrow S^1$

Note : the Jacobian can be defined even for $u \in H^{1/2}(\mathbb{S}, \mathbb{R}^2)$, and turns out to be the only obstruction to lifting [see: Han-Lin, Rivière, ...]

The problem of approximation for maps

$u \in W^{1,p}(\mathcal{B}, M)$ has been studied by Bethuel
↑
unit ball in \mathbb{R}^n K-dimensional manifold

(characterization of all p, M such that approx. exists),

Further studies by many others (Brezis-Lin,...)

For $u \in W^{1,p}(\mathcal{B}^k, S^{k-1})$, $k-1 \leq p < k$, the Jacobian is the obstruction to approximation....

Example : $W^{1,p}(\mathcal{B}^k, S^{k-1})$:

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ONE FINAL QUESTION

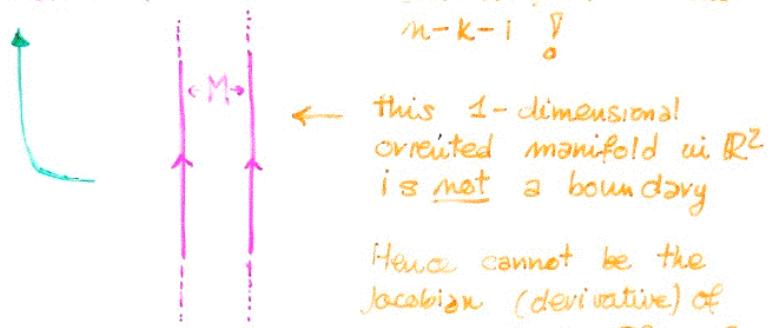
Given M $(n-k)$ -dimensional manifold without boundary in \mathbb{R}^n more generally:
 is there $u: \mathbb{R}^n \rightarrow S^{k-1}$ $(n-k)$ -polyhedral current
 smooth outside M such that

$$\star Ju = \alpha_k M$$

ANSWER [Alberti - Baldo - Orlandi]: $\alpha_1[M, \sim g_M, \{ \}]$ more precisely

YES FOR K = 2

YES (AND NO) FOR $K > 2 \leftarrow$ One must allow for an additional singularity (besides H) of dimension $n - K - 1$



Similar question:

GIVEN M $(n-k)$ -dimensional integral boundary
in $\Sigma \subset \mathbb{R}^n$ (or even $M = \text{bdry of integral multiplicity}$
rectifiable current), is there $u \in W^{k,1}(\Sigma, S^{k-1})$
s.t.

$$\star Tu = \alpha_k H$$

ANSWER [A-B-07]: YES FOR $K \geq 2$!

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AN INTERESTING GEOMETRIC CONSTRUCTION FOR $K=2$

Given M smooth, oriented, without boundary in \mathbb{R}^n and dimension $n-2$, we want to find

$\theta \in W^{1,1}(\mathbb{R}^n, \mathbb{R}/\mathbb{Z})$ smooth outside M such that

$$(1) \quad \star d(p\theta) = [M, \varphi_M, \pm]$$

The desired map α will be $\alpha := e^{2\pi i \theta}$

Setting $w := de$, equation (1) becomes

$$(2) \quad \int_M w \cdot \tau_\gamma = \text{Link}(M, \gamma) \leftarrow \begin{array}{l} \text{tangent to } \gamma \\ \text{1-form} \end{array} \quad \begin{array}{l} \text{Linking number} \\ \text{of } M \text{ and } \gamma \end{array}$$

for every curve γ in $\mathbb{R}^n \setminus M$

WE JUST CONSTRUCT ω SATISFYING (2).
IT WILL (AUTOMATICALLY!) BE OF THE FORM $\omega = d\theta$.

By definition

$$\text{Link}(M, \gamma) = \deg(\Phi; M \times \gamma, S^{k-1}) =$$

$$= \int_{M \times \mathbb{R}} \Phi^\# \tilde{\omega}$$

$\Phi(x,y) = \frac{x-y}{|x-y|}$
 Standard volume form on S^{k-1}

$$= \int_Y \left[\int_M (\Phi^\# \tilde{\omega})(x, y) \cdot \tau_H(x) \right] \cdot \tau_Y(y)$$

HENCE IT SUFFICES TO SET $\alpha^{(k-1)}$ -form applied to
 $\alpha^{(k-2)}$ -vector = 1-form ∇

$$\omega(y) = \int_M (\Phi^* \tilde{\omega})(x, y) \cdot \tau_H(x)$$

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see my webpage

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Higher Variation [INDIANA]

G.A.-Baldo-Orlandi: Maps with
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