

GMT 19/20

Lecture 1 12/3/20

Intro.

Structure of course

Part 1

- Hausdorff measures and dim.
- Lipschitz maps and area formula
- Rectifiable sets

part 2

- Currents (or Finite Rev. Sets)
and solution of Plateau Pb.

Plateau Problem



"Find the surface Σ
with minimal area
 \hookrightarrow $\text{cl-dim. surface in } \mathbb{R}^n \text{ (or } M^n)$

that spans a given curve Γ ,
cl-dim. volume \hookrightarrow $(d-1)$ -dim. surf.

- "Find,?" means "prove the existence of,"
- general dimension and codimension.

The problem is actually not well defined.

- What is a surface Σ ?
- What is Area?
- What is the meaning of " Σ spans \mathbb{R}^n "?

Clear answer if we restrict to regular objects.

But in the class of regular objects it is difficult to prove existence, and sometimes there is NO existence

(There are also modelling reasons to consider more general objects!)

Concerning existence: direct method
of Calc. Var. that is:

"seminicontinuity and compactness,"

Basic example:

$$\begin{cases} \Delta u = 0 & \text{on } \Omega \\ u = u_0 & \text{on } \partial\Omega \end{cases} \quad \text{no given}$$

$$F(u) := \int_{\Omega} \frac{1}{2} |\nabla u|^2 dx$$

minimize $F(u)$ on

$$W_{u_0}^{1,2}(\Omega)$$

then you prove regularity of u ,
and recover a classical sol.

For Plateau Ph. we need to find

- A compactification of surfaces
- a l.s.c. extension of the area functional
- an extension of the notion of bdry which is stable
- prove regularity (if possible).

That's what the theory of currents is about.

This is not the only possible approach!

Quick review of other approaches

- Purely set-theoretic approach

An example

$d=1$ (Steiner problem)

“Find the connected compact set Σ with minimal length 1-dim. H^1
Hausdorff meas. that contains a given (finite?) set Γ ,

Solution by direct method.

$$\mathcal{X} = \{ \Sigma \text{ compact, connected, } \Sigma \supset \Gamma \}$$

d_H = Hausdorff distance

H^1 is l.s.c. on \mathcal{P} ! (Golab's Th.)

Existence of minimizers is easy!

Reur

$$\begin{array}{c} \cdot \quad \Sigma_0 \\ \cdot \quad \vdots \quad \cdot \quad \Sigma_1 \\ \hline \vdots \quad \vdots \quad \vdots \quad \Sigma \end{array}$$

$$\Sigma_u \xrightarrow{d_H} \Sigma$$

semicontinuity of length wrt d_H fails!!

What about higher d ?

(Gjelab's theorem has no equivalent!)

A attempt of extension

Γ given curve

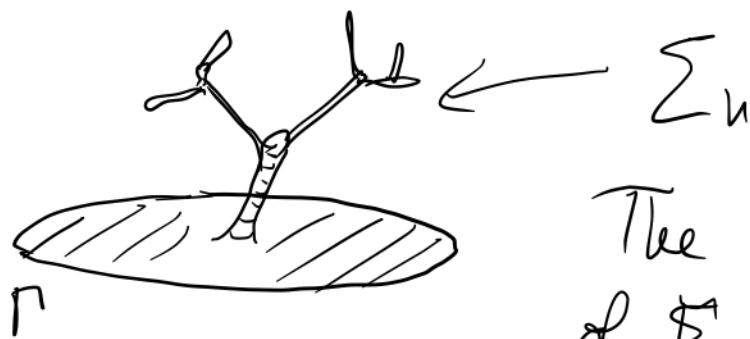
Σ compact set such that

$\Gamma \subset \Sigma$ & Γ can be retracted
to a point in Σ

This is a good class of sets

(compact wrt d_H if some
boundedness is assumed)

But area is not E.S.C.



The limit in d_H
of Σ_n can be
any closed set
containing the disk Σ

This \leftarrow approach (purely set theoretic)
was followed by Reifenberg in 1960

Proof is highly non trivial.

Variants of this approach proposed by
others

Harrison (+ De Lellis, Ghiraldin, Maggi)
after 2000

2 | Parametric Approach

Fix D model/reference surface
(disk in the plane, or some other d -dimensional domain)

Fix $\Gamma := \gamma(\partial D)$, $\gamma: \partial D \rightarrow \mathbb{R}^n$
given

let $\Sigma := \phi(D)$, $\phi: D \rightarrow \mathbb{R}^n$

Then " Σ spans Γ ", translate into
the bdry condition $\phi = \gamma$ on ∂D .

Moreover

$$\text{vol}_d(\Sigma) \underset{\text{if } \phi \text{ is injective}}{\simeq} \int_D J\phi \, ds \leftarrow F(\phi)$$

$$\begin{aligned} \text{if } d=2 \\ n=3 \end{aligned} \longrightarrow = \int_D \left[\frac{\partial \phi}{\partial s_1} \times \frac{\partial \phi}{\partial s_2} \right] ds_1 ds_2$$

minimize $F(\phi)$ over all $\phi: D \rightarrow \mathbb{R}^n$
s.t. $\phi = \gamma$ on ∂D .

Try to find a minimizer on
some Sobolev Space, e.g. $W_g^{1,2}(\mathbb{D})$

What is the problem?

- F is policonvex and therefore weakly l.s.c. on $W_g^{1,2}(\mathbb{D})$
- but F lacks coercivity.

What does this mean?

F is invariant by reparametrz.

$$F(\phi \circ \sigma) = F(\phi) \quad \forall \sigma: \mathbb{D} \rightarrow \mathbb{D}$$

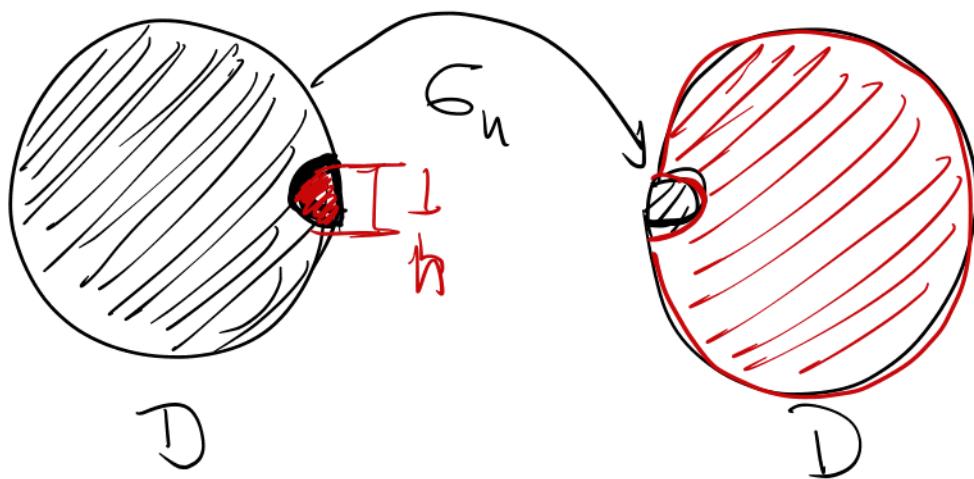
diffeo.

Using this fact I can construct minimizing sequences ϕ_n of F that converge to "very bad," ϕ .

For example, let ϕ be a minimizer of F .

Then any sequence $\phi_n = \phi \circ \sigma_n$ with $\sigma_n : D \rightarrow D$ diffeo is a minimizing seq.

I can choose σ_n so that the limit of $\phi \circ \sigma_n$ is constant!



$\phi \circ \sigma_n \rightarrow$ constant map.

No COMPACTNESS of minimizing seq.

The parametric approach works in dimension $d=1$ and $d=2$

Why?

$d=1$ $\Gamma = \{x_0, x_1\}$, find the geodesic connecting x_0 and x_1 (on some ambient space M^n which is a Riem. man.)

You minimize

$$F(\phi) = \cancel{\int_0^1 |\phi'(s)| ds}$$

$$E(\phi) = \int_0^1 [\phi'(s)]^2 ds \text{ on } W^{1,2}(D)$$

the minimizer ϕ of $E(\phi)$ is also a minimizer of $F(\phi) + \underline{|\phi'| is constant}$

Explanation

$$1) \quad E(\phi) = \int_0^1 |\phi'|^2 ds$$

Jensen $\rightarrow \geq \left(\int_0^1 |\phi'| ds \right)' = (L(\phi))^2$

= holds if $|\phi'|$ is constant!

2) Every $\phi : D = [0,1] \rightarrow \mathbb{R}^d$ admits
a reparametrization $\tilde{\phi} := \phi \circ \sigma$
with constant speed ($|\tilde{\phi}'| = \text{const.}$)

3) Let ϕ_0 be a minimizer of E .
Let ϕ be a competitor for E
then

$$\textcircled{L^2(\phi)} = L^2(\tilde{\phi}) = E(\tilde{\phi}) \geq E(\phi_0)$$

$\Rightarrow \phi_0$ minimizes L

$$\geq \textcircled{L^2(\phi_0)}$$

\Rightarrow if $\phi = \phi_0$ then $E(\phi_0) = L^2(\phi_0) \Rightarrow |\phi'_0| = \text{const.}$

A similar trick works for $d=2$

$\cdot D = \text{disk} = \overline{B(0,1)} \text{ in } \mathbb{R}^2$

$\cdot \phi : D \rightarrow \mathbb{R}^3 \quad F(\phi) = \int_D \left| \frac{\partial \phi}{\partial s_1} \times \frac{\partial \phi}{\partial s_2} \right| ds$

$\cdot E(\phi) = \int_D \frac{1}{2} |\nabla \phi|^2 ds = \int_D \frac{1}{2} \left(\left| \frac{\partial \phi}{\partial s_1} \right|^2 + \left| \frac{\partial \phi}{\partial s_2} \right|^2 \right) ds$

The a minimizer of $E(\phi)$

on the class $W^{1,2}(D)$ is a

also a minimizer of F .

Proof

$\phi = \gamma$
on ∂D
up to reparam.
of $\partial D = S^1$

$$1) E(\phi) = \int_D \frac{1}{2} \left(\left| \frac{\partial \phi}{\partial s_1} \right|^2 + \left| \frac{\partial \phi}{\partial s_2} \right|^2 \right) ds$$

$$\stackrel{\text{"iff}}{=} \left| \frac{\partial \phi}{\partial s_1} \right| = \left| \frac{\partial \phi}{\partial s_2} \right| \rightarrow \geq \int_D \left| \frac{\partial \phi}{\partial s_1} \right| \left| \frac{\partial \phi}{\partial s_2} \right| ds$$

$$\stackrel{\text{"iff}}{=} \left| \frac{\partial \phi}{\partial s_1} \times \frac{\partial \phi}{\partial s_2} \right| ds = F(\phi)$$

$\frac{\partial \phi}{\partial s_1} \perp \frac{\partial \phi}{\partial s_2}$ $E(\phi) = F(\phi)$ iff $d\phi(s)$ is conformal

2] For every Σ param. by ϕ

there exists a reparam.

σ is $\tilde{\phi} := \phi \circ \sigma$, $\sigma: D \rightarrow D$

not necen. s.t. $\tilde{\phi}$ is conformal

the identity (that is, $E(\tilde{\phi}) = F(\tilde{\phi})$)
on ∂D

(Lichtenstein theorem.)

3] Same proof as before!

This parametric approach was developed by Douglas & Radó in 1930s.

It only work for $d=2$

Because of lack of conformal parametrizations in dimension $d>2$.